

Failure in granular materials based on acoustic tensor: a numerical analysis

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Abstract. We investigate localization in granular material with the support of numerical simulations based upon DEM (Distinct Element Method). Localization is associated with a discontinuity in a component of the incremental strain over a plane surface through the condition of the determinant of the acoustic tensor to be zero. DEM simulations are carried out on an aggregate of elastic frictional spheres, initially isotropically compressed and then sheared at constant pressure p_0 . The components of the stiffness tensor are evaluated numerically in stressed states along the triaxial test and employed to evaluate the acoustic tensor in order to predict localization. This occurs in the pre-peak region, where the aggregate hardens under the circumstance to be incrementally frictionless: it is a regime in which the tangential force does not change as the deformation proceeds and, consequently, the deviatoric stress varies only with the normal component of the contact force.

1 Introduction

In a recent contribution, La Ragione et al. [1] analyze and predict localization in an ideal granular material based upon micro-mechanical considerations. They point out that failure is associated with a regime of deformation in which the incremental tangential forces become negligible. It is the possibility to describe the phenomena at particle level, including a more sophisticated kinematics between particles and their equilibrium [2, 3], that allows to predict when localization occurs and under which conditions. This is done in the context of the model proposed by Rudnicki and Rice [4], Vardoulakis [5, 6], in which localization is associated with the vanishing of the acoustic tensor. A different approach is proposed by Nicot and coauthors [7, 8] as they focus on the vanishing of the second-order work and the possibility to predict diffuse bifurcation. This phenomena may precede localization [9] but both second-order work and determinant of the acoustic tensor are zero when localization occurs. Here we focus on the acoustic tensor and evaluate the effective moduli via numerical simulations, following Recchia et al. [10]. We show that localization is plausible in a regime of deformation where the incremental material behavior is governed by normal forces.

In the present contribution, we briefly review the theory and the essential condition for localization. Next we employ numerical simulations to mimic a triaxial compression test for an ideal granular material and we evaluate the components of the stiffness tensor in stressed states along the main path. Finally, we use such components to verify under which conditions localization may occur.

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A video is available at <https://doi.org/10.48448/38sy-6h06>

2 Theory

We focus on an ideal elastic frictional aggregate of particles that has been isotropically compressed and next sheared. We label with y_1 the vertical axis of compression while in the orthogonal plane we consider the other two directions y_2 and y_3 such that y_1, y_2 and y_3 is a proper orthogonal, rectangular Cartesian coordinate system. The loading is axially symmetric so we restrict our attention to the $y_3 - y_1$ plane.

Following [4], localization occurs when the determinant of the acoustic tensor vanishes:

$$\det [l_i A_{ijpq} l_q] = 0, \quad (1)$$

where $\mathbf{l} = (0, -\sin(\Psi), \cos(\Psi))$ is the unit vector normal to the plane of discontinuity, see Fig. 1. The stiffness tensor, A_{ijqp} , relates the increments in stress to the increments in total average strain as

$$\Delta \sigma_{ij} = A_{ijpq} \Delta \epsilon_{pq}, \quad (2)$$

and assumes the form

$$\begin{aligned} A_{ijqp} = & \eta_1 h_i h_j h_q h_p + \eta_2 \delta_{ij} \delta_{qp} \\ & + \eta_3 (\delta_{iq} \delta_{jp} + \delta_{ip} \delta_{jq}) \\ & + \eta_4 \delta_{pq} h_i h_j + \eta_5 \delta_{ij} h_p h_q + \\ & + \eta_6 (\delta_{iq} h_j h_p + \delta_{ip} h_j h_q + \delta_{jp} h_i h_q + \delta_{jq} h_i h_p). \end{aligned} \quad (3)$$

Because of the loading condition, the aggregate is transversely isotropic and depends on the six coefficients η_i [11]. Eq. (1) is equivalent to

$$(T_1 \cos^4 \Psi + T_2 \cos^2 \Psi + T_3)(\eta_6 \cos^2 \Psi + \eta_3) = 0, \quad (4)$$

which leads to the solutions [1]:

$$\cos^2 \Psi_{1,2} = \frac{-T_2 \pm \sqrt{T_2^2 - 4T_1 T_3}}{2T_1}, \quad (5)$$

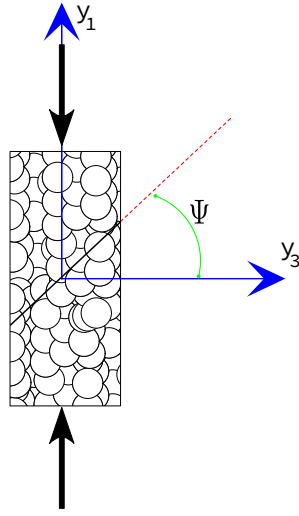


Figure 1. Schematic of a granular aggregate compressed in the direction y_1 , with a shear band formed in the plane y_1, y_3 .

with

$$T_1 = (A_{1111} - A_{1212})(A_{1212} - A_{3333}) + (A_{1212} + A_{1133})(A_{1212} + A_{3311}), \quad (6)$$

$$T_2 = (A_{1111} - A_{1212})A_{3333} + (A_{1212} - A_{3333})A_{1212} - (A_{1212} + A_{1133})(A_{1212} + A_{3311}) \quad (7)$$

and

$$T_3 = A_{1212}A_{3333}. \quad (8)$$

Localization occurs when the discriminant in Eq. (5) is zero. Then, the angle of localization is

$$\cos\Psi = \sqrt{\frac{-T_2}{2T_1}}. \quad (9)$$

In the next section we carry out numerical simulations to evaluate the components A_{ijqp} of the stiffness tensor of the aggregate.

3 DEM simulation

DEM represents granular materials as packings of solid particles (often spheres) that are allowed to overlap [12]. The particles in contact interact with their neighbors via repulsive springs, resulting in momentum exchange between particles. If the contact forces, acting on a particle, are known the problem is reduced to the integration of Newton's equations of motion for the translational and rotational degrees of freedom of that particle.

The system considered here is a random assembly of identical, frictional, elastic spheres in which gravity is neglected. Particles interact through a non-central force with

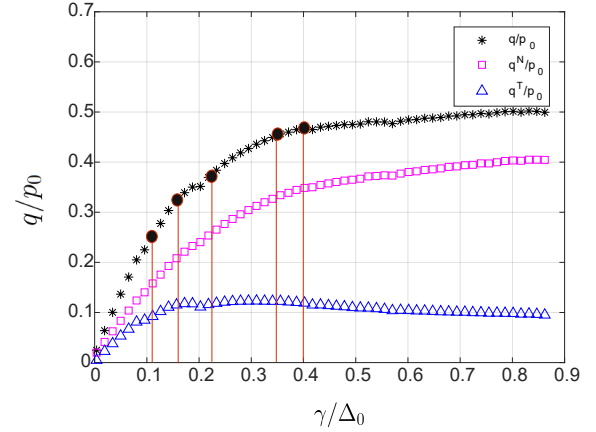


Figure 2. Normalized deviatoric stress, q/p_0 (black symbols), versus normalized deviatoric strain, γ/p_0 , and its components q_N/p_0 (magenta symbols) and q_T/p_0 (blue symbols).

a normal component that follows the non-linear Hertz law and a tangential component that includes a bilinear relation characterized by an elastic resistance followed by a Coulomb sliding. During the simulation, the average stress is calculated following the Cauchy relation for molecular systems (e.g. [10]).

Preparation protocol

We refer to material characteristics typical of glass spheres, with shear modulus $G_s = 29\text{GPa}$, Poisson's ratio, $\nu = 0.2$, and radius $R = 0.1\text{mm}$. At the beginning of the simulation, particles are randomly generated in a periodic cubic cell and then isotropically compressed to achieve a consolidated state. Compression happens in two stages. Initially the sample is compressed with friction coefficient $\mu = 0$, until a solid volume fraction $\phi \leq 0.64$ is reached; then, after relaxation, a second compression follows with $\mu = 0.5$, that brings the aggregate to the target isotropic pressure $p_0 = 200\text{kPa}$, with $\phi \geq 0.64$ (see [13] for details). In this reference isotropic configuration, the volumetric strain associated with the pressure p_0 is $\Delta_0 = 1 \times 10^{-3}$.

Axial-symmetric compression

After compression, the aggregate is sheared by applying strain along the axial direction y_1 , while the pressure $p_0 = 200\text{kPa}$ is kept constant by means of a servo-mechanism [13]. The test is carried out with $\mu = 0.5$. To ensure quasi-static conditions, the compression is performed with a sequence of small strain steps of the order of $\Delta\epsilon_{11} = 4 \times 10^{-6}$ followed by relaxation steps. In the latter, particles are allowed to dissipate kinetic energy and reach intermediate equilibrium states.

Along the compression path, we can extract the deviatoric strain as $\gamma = (\epsilon_{22} + \epsilon_{33})/4 - \epsilon_{11}/2$ and measure the deviatoric stress $q = (\sigma_{22} + \sigma_{33})/2 - \sigma_{11}$, as well as its normal and tangential parts, q_N and q_T , associated, with

the normal and tangential contact forces, respectively [14]. In Figure 2 we plot the normalized deviatoric stress q/p_0 against the normalized deviatoric strain γ/Δ_0 . In the same figure, the partitions q_N/p_0 and q_T/p_0 are shown as well. After an initial stage, it is clear that the deviatoric stress is almost identifiable with its normal component q_N , with the increments in q_T almost negligible. In particular, for $\gamma/\Delta_0 \gtrsim 0.3$ the tangential part of the deviatoric stress remains constant, i.e. $\dot{q}_T = 0$. This regime is characterized by a constant tangential force so that the resulting incremental force is only associated with its normal component. La Ragione et al. [1] define this regime *incrementally frictionless*. As well known in elasto-plasticity theory material yields both before and after the peak stress. We are in the pre-peak region in which plasticity is associated with q_T constant while q_N still increases indicating an hardening behavior of the aggregate until $\dot{q}^N = 0$ [14], [15].

Stiffness tensor

Along the compression path, we consider different stress states and evaluate the non zero components of the stiffness tensor. As shown in Recchia et al. [10], for each point, we apply strain perturbations $\Delta\epsilon_{pq}$ in the forward direction, i.e. consistent with loading along the triaxial stress path, so that if particles were sliding or rolling during the axial loading, they continue to do so during the probe. Then we measure the change in stress $\Delta\sigma_{ij}$ between the final state (after sufficient relaxation) and the stress before the perturbation. Finally, the stiffness components are given as

$$A_{ijpq} = \Delta\sigma_{ij}/\Delta\epsilon_{pq}. \quad (10)$$

For example, the moduli A_{1111} and A_{3311} are obtained by applying an infinitesimal perturbation along y_1 , $\Delta\epsilon_{11} \neq 0$, with $\Delta\epsilon_{22} = \Delta\epsilon_{33} = 0$, that leads to stress change along y_1 and y_3 , thus

$$A_{1111} = \Delta\sigma_{11}/\Delta\epsilon_{11} \quad \text{and} \quad A_{3311} = \Delta\sigma_{33}/\Delta\epsilon_{11}. \quad (11)$$

Similarly, the moduli A_{1133} and A_{3333} are calculated with a perturbation along y_3 , with $\Delta\epsilon_{11} = \Delta\epsilon_{22} = 0$, as

$$A_{1133} = \Delta\sigma_{11}/\Delta\epsilon_{33} \quad \text{and} \quad A_{3333} = \Delta\sigma_{33}/\Delta\epsilon_{33}. \quad (12)$$

Finally, we verify that

$$A_{1122} = A_{1133}, \quad A_{2222} = A_{3333}, \quad A_{2211} = A_{3311}, \quad (13)$$

due to axial-symmetry.

As an example, in Figure 3 we show the evolution of the stiffness component A_{1111} with the strain amplitude. As reported in [10, 16, 17], the first plateau refers to the elastic response in which the perturbation is so small to prevent sliding and rolling among particles. The second plateau is associated with an inelastic, yet linear, incremental response, that preserves the micro- and macro-mechanisms happening during axial loading. We choose the latter as reference to build the acoustic tensor (i.e., we employ values of A_{ijkh} obtained with strain perturbations $\Delta\epsilon_{ij} \approx 5 \times 10^{-5}$) because we refer to probes that are similar to those considered during the uniaxial loading, when localization may occur.

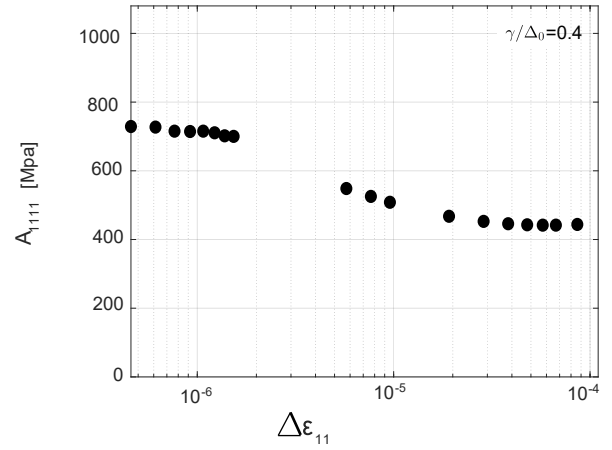


Figure 3. Stiffness component A_{1111} versus applied perturbation at stressed state corresponding with $\gamma/\Delta_0 = 0.4$.

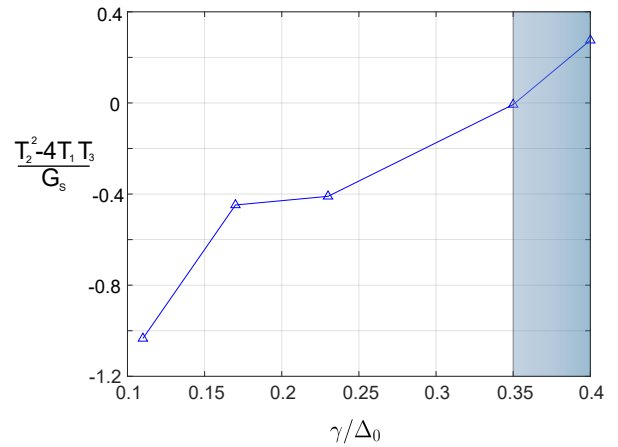


Figure 4. Normalized discriminant in Eq. (5) versus normalized deviatoric strain. The grey strip indicates the region where the discriminant changed sign.

4 Results: acoustic tensor

With the knowledge of the A_{ijkh} components at several stress states along the triaxial deformation, we can evaluate T_1 , T_2 and T_3 and calculate the discriminant of the acoustic tensor in Eq. (5), $T_2^2 - 4T_1T_3$, and its evolution with the strain.

In Figure 4 we plot the discriminant normalized by the particle shear modulus G_s versus the normalized shear strain γ/Δ_0 , evaluated in five stress states, as indicated also in Figure 2. The discriminant grows monotonically and changes sign for $\gamma/\Delta_0 > 0.35$ suggesting that localization may occur. It is interesting to note that the possibility of localization, thus failure, is here predicted in a region of deformation that precedes the stress peak. This is the regime in which q_T is constant while q_N keeps growing. Here, Recchia et al. [10] find, at contact level, that particles slide and roll confirming no increment in the tangential forces and supporting the idea that the increment in the

contact forces occurs only along the normal component. It is expected that in a later stage shear bands will occur with major fabric changes and dilatancy, with particles failing into (larger) gaps steadily. However such analysis is beyond the scope of the present study.

In the context of micro-mechanics, the recent contribution by Karapiperis et al. [18] provides a useful tool to have a detailed analysis at particle level and test theory like this. It may be also relevant to test how the shape of the particles in the aggregate, here idealized as identical elastic spheres, influences the onset of localization [19].

5 Conclusion

Along a triaxial test on an aggregate of identical, elastic, particles we have studied the evolution of the acoustic tensor and the possibility that the condition for localization is met. The analysis has been conducted by means of DEM numerical simulations. The components of the stiffness tensor have been evaluated by probing stressed, anisotropic, states via strain increments. We show that the determinant of the acoustic tensor vanishes before the peak of deviatoric stress is reached [20], in a regime characterized by the *incrementally frictionless* behavior of the aggregate. A sequel is in progress to visualize per-particle incremental shear strain, that should indicate the presence of a localization band in the same stress-strain region where failure is predicted.

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