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convolutions in \mathbf{R}^3**

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YOUNG INEQUALITY FOR SURFACE CONVOLUTIONS IN \mathbf{R}^3

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Abstract. We prove a Young inequality for convolutions defined on a Lipschitz continuous surface in \mathbf{R}^3 .

Key words. Young inequality, surface convolutions

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1. Introduction. In this paper we provide an estimate for the $L_p(\Omega)$ norm of a surface convolution defined at the boundary of a Lipschitz domain $\Omega \subset \mathbf{R}^3$. For $x \in \Omega$, the surface convolution is stated as:

$$x \rightarrow \int_{\partial\Omega} f(x-y)g(y) \, dS_y,$$

where $f \in L_q(\mathbf{R}^3)$, $g \in L_r(\mathbf{R}^3)$ with $q, r \geq 1$. For the proof of the main result (stated in Theorem 4) we use the classical results in [2] and [3], which are summarized in Section 2.

2. Preliminaries.

2.1. Young inequality in \mathbf{R}^n with a sharp constant. Although the Young inequality has been known for a long time, the present form was only proved in the 70's, independently in [2] and [3]:

THEOREM 1. *For real numbers $p, q, r \geq 1$ with $1 + \frac{1}{p} = \frac{1}{q} + \frac{1}{r}$ and functions $f \in L_q(\mathbf{R}^n)$, $g \in L_r(\mathbf{R}^n)$ we have the following inequality:*

$$\left(\int_{\mathbf{R}^n} \left| \int_{\mathbf{R}^n} f(x-y)g(y) \, dy \right|^p \, dx \right)^{\frac{1}{p}} = \|f * g\|_p \leq \left(\frac{C_q C_r}{C_p} \right)^n \|f\|_q \|g\|_r, \quad (2.1)$$

where $C_p = \sqrt{\frac{p^{\frac{1}{p}}}{p'^{\frac{1}{p'}}}}$ with $\frac{1}{p} + \frac{1}{p'} = 1$ and $C_1 = C_\infty = 1$.

Remark: Taking the limit $p \rightarrow 1$ gives the value for C_1 . This case is of a great importance since in many applications f is related to a fundamental solution of some differential operator (with a singularity) such that $f \notin L_q(\mathbf{R}^n)$ for $q > 1$.

For the proof of this theorem and further literature we refer [5] (pages 99-105).

2.2. The fully generalized Young inequality. In the meantime the result of Theorem 1 has been sharpened in two ways: the precise condition for equality in (2.1) has been provided and the inequality was generalized to a product of functions f_1, f_2, \dots, f_k (not necessarily for a convolution) which are defined on \mathbf{R}^{n_i} with different values of n_i instead of just taking f and g . We cite this general form of the inequality [4], [5] (page 100):

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THEOREM 2. Fix $k > 1$, integers n_1, n_2, \dots, n_k and numbers $p_1, p_2, \dots, p_k \geq 1$. Let $M \geq 1$ and let B_i (for $i = 1, 2, \dots, k$) be a linear mapping from \mathbf{R}^M to \mathbf{R}^{n_i} . Let $Z : \mathbf{R}^M \rightarrow \mathbf{R}^+$ be some fixed Gaussian function,

$$Z(x) = e^{-(x, Ax)}$$

with A a real, positive semidefinite $M \times M$ matrix (possibly zero) and (\cdot, \cdot) the Euclidian inner product in \mathbf{R}^M . For functions $f_i \in L_{p_i}(\mathbf{R}^{n_i})$ consider the integral

$$I_Z(f_1, f_2, \dots, f_k) = \int_{\mathbf{R}^M} Z(x) \prod_{i=1}^k f_i(B_i x) \, dx \quad (2.2)$$

and define

$$C_Z := \sup\{I_Z(f_1, f_2, \dots, f_k) : \|f_i\|_{p_i} = 1 \text{ for } i = 1, 2, \dots, k\}. \quad (2.3)$$

Then C_Z is determined by restricting the functions f_i to be Gaussian functions, i.e.,

$$C_Z := \sup\{I_Z(f_1, f_2, \dots, f_k) : \|f_i\|_{p_i} = 1 \text{ and } f_i(x) = e^{-(x, A_i x)} \text{ with } A_i \text{ a real, symmetric, positive definite } n_i \times n_i \text{ matrix}\}. \quad (2.4)$$

To get an alternative form of the classical Young inequality [5] take $A = 0$, $k = 3$, $B_1 = (1, 0)$, $B_2 = (1, -1)$ and $B_3 = (0, 1)$.

3. Young inequality for convolutions on manifolds.

3.1. Special case: Young inequality for integrals on $\mathbf{R}^n \times \mathbf{R}^{n-1}$. We first prove the following upper estimate for an integral related to the left hand side of (2.1):

$$\left(\int_{\mathbf{R}^n} \left| \int_{\mathbf{R}^{n-1}} f(x - y(u, 0))g(u) \, du \right|^p \, dx \right)^{\frac{1}{p}} \leq C \|f\|_{L_q(\mathbf{R}^n)} \|g\|_{L_r(\mathbf{R}^{n-1})}, \quad (3.1)$$

where $f \in L_q(\mathbf{R}^n)$, $g \in L_r(\mathbf{R}^{n-1})$, $x \in \mathbf{R}^n$, $u = (u_1, u_2, \dots, u_{n-1}) \in \mathbf{R}^{n-1}$ and $y(u, 0) = y(u_1, u_2, \dots, u_{n-1}, 0) \in \mathbf{R}^n$, while $C \in \mathbf{R}$ is a positive constant.

In order to apply the standard estimate (2.1) we introduce a nonnegative, real-valued function J belonging to $C_0^\infty(\mathbf{R}^n)$ having the properties:

$$J(x) = 0, \quad |x| \geq 1, \\ \int_{\mathbf{R}^n} J = 1.$$

For $\delta > 0$ we also define the mollifier $J_\delta = \delta^{-n} J(x/\delta)$ and $g_\delta : \mathbf{R}^n \rightarrow \mathbf{R}$ with $g_\delta(u, u_n) = g(u)J_\delta(u_n)$ for which $\int_{\mathbf{R}} g_\delta(u, u_n) \, du_n = g(u)$. Using these relations we rewrite the integral on the left hand side of (3.1) and obtain the following inequality; where in all formulae we use $u = (u_1, u_2, \dots, u_{n-1}) \in \mathbf{R}^{n-1}$ and $(u, u_n) =$

$(u_1, u_2, \dots, u_{n-1}, u_n) \in \mathbf{R}^n$:

$$\left(\int_{\mathbf{R}^n} \left| \int_{\mathbf{R}^{n-1}} f(x - y(u, 0))g(u) du \right|^p dx \right)^{\frac{1}{p}} \quad (3.2)$$

$$\begin{aligned} &= \left(\int_{\mathbf{R}^n} \left| \int_{\mathbf{R}^n} f(x - y(u, 0))g_\delta(u, u_n) du du_n \right|^p dx \right)^{\frac{1}{p}} \\ &= \left(\int_{\mathbf{R}^n} \left| \int_{\mathbf{R}^n} f(x - y(u, u_n))g_\delta(u, u_n) du du_n + \right. \right. \\ &\quad \left. \int_{\mathbf{R}^n} (f(x - y(u, 0)) - f(x - y(u, u_n)))g_\delta(u, u_n) du du_n \right|^p dx \right)^{\frac{1}{p}} \\ &\leq \left(\int_{\mathbf{R}^n} \left| \int_{\mathbf{R}^n} f(x - y(u, u_n))g_\delta(u, u_n) du du_n \right|^p dx \right)^{\frac{1}{p}} + \\ &\quad \left(\int_{\mathbf{R}^n} \left| \int_{\mathbf{R}^n} (f(x - y(u, 0)) - f(x - y(u, u_n)))g_\delta(u, u_n) du du_n \right|^p dx \right)^{\frac{1}{p}} \end{aligned} \quad (3.3)$$

using Minkowski's inequality. Following [1] (page 242) we define the p -mean modulus of continuity ω_p^* as:

$$\omega_p^*(v, t) = \sup_{|h| \leq t} \left(\int_{\mathbf{R}^n} |v(x+h) - v(x)|^p dx \right)^{\frac{1}{p}}, \quad \text{for } t > 0 \text{ and } 1 \leq p < \infty,$$

then for $1 \leq p < \infty$ we have the limit $\omega_p^*(v, t) \rightarrow 0$ as $t \downarrow 0$ for all $v \in L_p(\mathbf{R}^n)$.

Our aim is to take the limit $\delta \downarrow 0$ in (3.3) and apply (2.1). For this we prove the following:

LEMMA 1. For real numbers $p, q, r \geq 1$, with $1 + \frac{1}{p} = \frac{1}{q} + \frac{1}{r}$ and $p < \infty$, and functions $f \in L_q(\mathbf{R}^n)$ and $g_\delta \in L_r(\mathbf{R}^n)$ we have

$$\lim_{\delta \downarrow 0} \left(\int_{\mathbf{R}^n} \left| \int_{\mathbf{R}^n} (f(x - y(u, 0)) - f(x - y(u, u_n)))g_\delta(u, u_n) du du_n \right|^p dx \right)^{\frac{1}{p}} = 0$$

Proof: Applying Minkowski's inequality for integrals (Theorem 2.9 in [1]) and the convergence result for the p -mean modulus of continuity we obtain:

$$\begin{aligned} &\left(\int_{\mathbf{R}^n} \left| \int_{\mathbf{R}^n} (f(x - y(u, 0)) - (x - y(u, u_n)))g_\delta(u, u_n) du du_n \right|^p dx \right)^{\frac{1}{p}} \\ &\leq \int_{\mathbf{R}^n} \left(\int_{\mathbf{R}^n} \left| (f(x - y(u, 0)) - f(x - y(u, u_n)))g_\delta(u, u_n) \right|^p dx \right)^{\frac{1}{p}} du du_n \\ &= \int_{\mathbf{R}^{n-1}} |g(u)| \left(\int_{-\delta}^{\delta} J_\delta(u_n) \left(\int_{\mathbf{R}^n} |f(x - y(u, 0)) - f(x - y(u, u_n))|^p dx \right)^{\frac{1}{p}} du_n \right) du \\ &\leq \int_{\mathbf{R}^{n-1}} |g(u)| \left(\int_{-\delta}^{\delta} J_\delta(u_n) du_n \omega_p^*(f, \delta) \right) du \\ &= \omega_p^*(f, \delta) \|g\|_{L_1(\mathbf{R}^{n-1})} \rightarrow 0 \quad \text{as } \delta \downarrow 0. \quad \square \end{aligned}$$

We can now prove (3.1) and give an upper bound for the constant C .

THEOREM 3. For real numbers $p, q, r \geq 1$, with $1 + \frac{1}{p} = \frac{1}{q} + \frac{1}{r}$ and $p < \infty$, and functions $f \in L_q(\mathbf{R}^n)$ and $g \in L_r(\mathbf{R}^{n-1})$ the following inequality holds:

$$\left(\int_{\mathbf{R}^n} \left| \int_{\mathbf{R}^{n-1}} f(x - y(u, 0))g(u) \, du \right|^p dx \right)^{\frac{1}{p}} \leq \left(\frac{C_q C_r}{C_p} \right)^n \|f\|_{L_q(\mathbf{R}^n)} \|g\|_{L_r(\mathbf{R}^{n-1})}, \quad (3.4)$$

where $C_p = \sqrt{\frac{\frac{1}{p}}{p^{\frac{1}{p}} p'^{\frac{1}{p'}}}}$ with $\frac{1}{p} + \frac{1}{p'} = 1$ and $C_1 = C_\infty = 1$.

Proof: Taking the limit $\delta \downarrow 0$ and applying the result of Lemma 1, then using Theorem 1 and the relation $\|g_\delta\|_{L_r(\mathbf{R}^n)} = \|g\|_{L_r(\mathbf{R}^{n-1})}$, we can estimate (3.2) as follows:

$$\begin{aligned} & \left(\int_{\mathbf{R}^n} \left| \int_{\mathbf{R}^{n-1}} f(x - y(u, 0))g(u) \, du \right|^p dx \right)^{\frac{1}{p}} \\ &= \lim_{\delta \downarrow 0} \left(\int_{\mathbf{R}^n} \left| \int_{\mathbf{R}^n} f(x - y(u, u_n))g_\delta(u, u_n) \, du \, du_n \right|^p dx \right)^{\frac{1}{p}} \\ &\leq \lim_{\delta \downarrow 0} \left(\frac{C_q C_r}{C_p} \right)^n \|f\|_{L_q(\mathbf{R}^n)} \|g_\delta\|_{L_r(\mathbf{R}^n)} \\ &= \left(\frac{C_q C_r}{C_p} \right)^n \|f\|_{L_q(\mathbf{R}^n)} \|g\|_{L_r(\mathbf{R}^{n-1})}. \quad \square \end{aligned} \quad (3.5)$$

Remark: Since we proved inequality (3.1) for functions g_δ which are never Gaussian functions, Theorem 2 shows that one can expect a sharper constant than the one given by Theorem 3.

3.2. General case: Young inequality for surface convolutions in \mathbf{R}^3 . In the following we investigate the case when g is defined on the surface $\Gamma_i \subset \partial\Omega$ of a bounded domain Ω determined by $l_i : \mathbf{R}^2 \rightarrow \mathbf{R}$, a Lipschitz continuous function with Lipschitz constant L_i , such that

$$\Gamma_i = \{(u, l_i(u)) : u \in G_i\} \quad (3.6)$$

for some open set $G_i \subset \mathbf{R}^2$. We make use of the following definitions:

DEFINITION 3.1. For $f \in L_q(\Omega \dot{+} (-\Omega))$, with $q \geq 1$ and a domain $\Omega \subset \mathbf{R}^3$, we introduce $f_\Omega \in L_q(\mathbf{R}^3)$ with:

$$f_\Omega(x) = \begin{cases} f(x), & x \in \Omega \dot{+} (-\Omega) \\ 0, & x \notin \Omega \dot{+} (-\Omega), \end{cases} \quad (3.7)$$

where $\Omega \dot{+} (-\Omega) = \{x - y : x, y \in \Omega\}$.

DEFINITION 3.2. For $g \in L_r(S)$, with $r \geq 1$ and $S \subset \mathbf{R}^3$, we introduce $g_S \in L_r(\mathbf{R}^3)$ with:

$$g_S(x) = \begin{cases} g(x), & x \in S \\ 0, & x \notin S. \end{cases} \quad (3.8)$$

DEFINITION 3.3. For $l_i \in \text{Lip}(G_i)$, with $r \geq 1$ and $G_i \subset \mathbf{R}^2$, we introduce $m_i \in L_\infty(\mathbf{R}^2)$ with:

$$m_i(u) = \begin{cases} \sqrt{1 + |\text{grad } l_i(u)|^2}, & u \in G_i \\ 0, & u \notin G_i. \end{cases} \quad (3.9)$$

Using (3.7) and (3.8) for the case when $S \subset \overline{\Omega}$ we obtain that

$$f(x-y)g(y) = f_\Omega(x-y)g(y) = f_\Omega(x-y)g_S(y) \quad (3.10)$$

holds for any $x \in \Omega$ and $y \in S$.

Using these results we formalize the estimate for surface integrals in \mathbf{R}^3 .

THEOREM 4. Consider the boundary surface $\Gamma \subset \partial\Omega$ of a domain $\Omega \subset \mathbf{R}^3$, which is covered almost everywhere with a finite number of disjoint surfaces Γ_i (each of them is the graph of a Lipschitz function given in (3.6)), i.e. $\lambda(\Gamma \setminus \cup_{i=1}^N \Gamma_i) = 0$, where λ is the Lebesgue measure on the surface $\partial\Omega$. Let $f \in L_q(\Omega \dot{+} (-\Omega))$ and $g \in L_r(\Gamma)$, then for real numbers $p, q, r \geq 1$, with $1 + \frac{1}{p} = \frac{1}{q} + \frac{1}{r}$ and $p < \infty$, we have the relation:

$$\left\| \int_\Gamma f(x-y)g(y) \, dS_y \right\|_{L_p(\Omega)} \leq \left(\frac{C_q C_r}{C_p} \right)^3 \|f\|_{L_q(\Omega \dot{+} (-\Omega))} \sum_{i=1}^N (1 + L_i^2)^{(r-1)/2r} \|g\|_{L_r(\Gamma_i)}. \quad (3.11)$$

Proof: Using Definitions 3.1, 3.2 and 3.3 we can estimate the norm of the surface integral on Γ_i (given in (3.6)) as follows:

$$\begin{aligned} & \left\| \int_{\Gamma_i} f(x-y)g(y) \, dS_y \right\|_{L_p(\Omega)} = \left(\int_\Omega \left| \int_{\Gamma_i} f(x-y)g(y) \, dS_y \right|^p dx \right)^{\frac{1}{p}} \\ & \leq \left(\int_{\mathbf{R}^3} \left| \int_{\Gamma_i} f_\Omega(x-y)g(y) \, dS_y \right|^p dx \right)^{\frac{1}{p}} \\ & = \left(\int_{\mathbf{R}^3} \left| \int_{G_i} f_\Omega(x-y(u,0))g(y(u,0))\sqrt{1 + |\text{grad } l_i(u)|^2} \, du \right|^p dx \right)^{\frac{1}{p}} \\ & \leq \left(\int_{\mathbf{R}^3} \left| \int_{\mathbf{R}^2} f_\Omega(x-y(u,0))\tilde{g}_{\Gamma_i}(u)m_i(u) \, du \right|^p dx \right)^{\frac{1}{p}} \quad (3.12) \\ & \leq \left(\frac{C_q C_r}{C_p} \right)^3 \|f_\Omega\|_{L_q(\mathbf{R}^3)} \|\tilde{g}_{\Gamma_i} m_i\|_{L_r(\mathbf{R}^2)} \\ & = \left(\frac{C_q C_r}{C_p} \right)^3 \|f\|_{L_q(\Omega \dot{+} (-\Omega))} \left(\int_{G_i} |g(u, l_i(u))|^r \left| \sqrt{1 + |\text{grad } l_i(u)|^2} \right|^r du \right)^{\frac{1}{r}} \\ & \leq (1 + L_i^2)^{(r-1)/2r} \left(\frac{C_q C_r}{C_p} \right)^3 \|f\|_{L_q(\Omega \dot{+} (-\Omega))} \|g\|_{L_r(\Gamma_i)}, \end{aligned}$$

where in the third inequality we applied Theorem 3. In addition, we have used the relations $y(u,0) = T(u, l_i(u))$, with $T: \mathbf{R}^3 \rightarrow \mathbf{R}^3$ a linear mapping, $\tilde{g}_{\Gamma_i}(u) = g_{\Gamma_i}(y(u,0))$ and L_i denotes the Lipschitz constant of l_i . Next we consider the decomposition Γ into subdomains:

$$\Gamma = \Gamma_1 \cup \Gamma_2 \cup \dots \cup \Gamma_N \cup R, \quad (3.13)$$

where $\lambda(R) = 0$ with the surface measure λ according to (3.6) and to the assumptions in the theorem. Taking the sum of the inequalities in (3.12) for $i = 1, 2, \dots, N$ we obtain that

$$\begin{aligned} \left\| \int_{\Gamma} f(x-y)g(y) \, dS_y \right\|_{L_p(\Omega)} &\leq \sum_{i=1}^N \left\| \int_{\Gamma_i} f(x-y)g(y) \, dS_y \right\|_{L_p(\Omega)} \\ &\leq \left(\frac{C_q C_r}{C_p} \right)^3 \|f\|_{L_q(\Omega \dot{+} (-\Omega))} \sum_{i=1}^N (1 + L_i^2)^{(r-1)/2r} \|g\|_{L_r(\Gamma_i)}. \end{aligned} \quad (3.14)$$

□

3.3. Examples.

1. Ω is a bounded polyhedron with closed faces $\overline{F_1}, \overline{F_2}, \dots, \overline{F_N} \subset \partial\Omega$ and we define $\Gamma_i = \text{int}(F_i)$. Then clearly, we can define $l_i : \mathbf{R}^2 \rightarrow \mathbf{R}^3$ as a constant function such that the right hand side in (3.14) is $\left(\frac{C_q C_r}{C_p} \right)^3 \|f\|_{L_q(\Omega \dot{+} (-\Omega))} \|g\|_{L_r(\Gamma)}$.
2. Ω is a curvilinear polyhedron with closed faces $\overline{F_1}, \overline{F_2}, \dots, \overline{F_N} \subset \partial\Omega$ such that $\text{int}(F_i)$ is the map of a Lipschitz function with $\text{int } F_i = \{(y, l_i(y)) : y \in G_i\}$, where $\lambda(\partial G_i) = 0$ with λ the Lebesgue measure in \mathbf{R}^2 .

Using the definition of the surface measure an easy calculation gives that the surface measure of the boundaries ∂F_i is zero, as well. According to the assumptions in Theorem 4 this gives the decomposition

$$\partial\Omega = F_1 \cup F_2 \cup \dots \cup F_N \cup \bigcup_{i=1}^N \partial F_i.$$

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