

# Analytical Design Equations for Class-E Power Amplifiers with Finite DC-Feed Inductance and Switch On-Resistance

Mustafa Acar, Anne Johan Annema and Bram Nauta  
IC Design Chair, University of Twente, The Netherlands

**Abstract**—Many critical design trade-offs of the Class-E power amplifier (e.g power efficiency) are influenced by the switch on-resistance and the value of dc-feed drain inductance. In literature, the time-domain mathematical analyses of the Class-E power amplifier with finite dc-feed inductance assume zero switch on-resistance in order to alleviate the mathematical difficulties; resulting in non-optimum designs.

We present analytical design equations in this paper for Class-E power amplifier taking into account both finite drain inductance and switch on-resistance. The analysis indicates the existence of infinitely many design equations; conclusions include:

- 1) Class-E conditions (e.g. zero voltage and zero slope) can be satisfied in the presence of switch-on resistance.
- 2) The drain-efficiency ( $\eta$ ) of the Class-E power amplifier is upper limited for a certain operation frequency and transistor technology.
- 3) Using a finite dc-feed inductance instead of an RF-choke in a Class-E power amplifier can increase  $\eta$  by  $\approx 30\%$ .

## I. INTRODUCTION

The Class-E power amplifier (PA) has been very popular due to its high efficiency and the simple circuit structure [1]. However, the "finite dc-feed inductance" and the "non-zero switch on-resistance" significantly influence the performance of the Class-E PAs [2]. To alleviate the analytical complexity, theoretical analyses of the Class-E PA in the literature assumed either non-zero switch-on resistance and infinite dc-feed inductance (RF-choke) [3]- [7] or zero switch-on resistance and finite dc-feed inductance [8]- [11].

It is well-known that using a finite dc feed inductance instead of an RF-choke in Class-E has benefits [8], [9] including:

- a reduction in overall size and cost
- a higher load resistance for the same supply voltage and output power; yielding more efficient output matching networks
- larger switch parallel capacitor  $C$  (Fig.1a) for the same supply voltage, output power and load; enabling higher drain efficiency or higher frequency of operation.

In order to design Class-E PAs with optimum performance an improved analytical model that takes into account both the finite drain inductance and non-zero switch on-resistance is therefore needed [2].

In [12]- [21] the switch on-resistance is taken into account in the design of Class-E PAs. In [12], the shunt capacitor ( $C$  see Fig.1b) is assumed to be disconnected at the switch turn-off

moment; which makes the analysis only an approximation. In [13], the shunt capacitor voltage ( $V_C(t)$ ) is assumed to be zero at the switch turn-off moment; which is not analytically exact and can be accepted only for very small switch on-resistance ( $R_{on} \ll R$ ).

The analysis and the design approach given in [14] offers no initial design guidelines, which tends to make it tedious because of the inherently large number of iterations that are required [5].

Moreover, the design methodologies presented in [15]- [20] either relies on iteration [15]- [19] or assigning initial values to some design variables [20]. In [21], an analytical solution for a sub-class of Class-E PA <sup>1</sup> is presented.

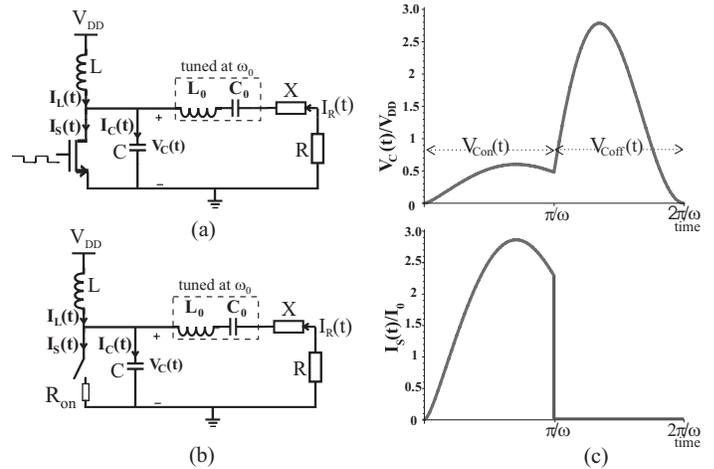


Fig. 1. (a) Single-ended Class-E PA (b) Model of Class-E PA with finite dc-feed inductance and switch on-resistance (c) Normalized switch (transistor) voltage and current for the model of Class-E PA

This paper presents an analysis (time domain) and design equations for Class-E PAs with *finite dc-feed inductance* and *non-zero switch on-resistance*. The analysis in this paper is based on closed form expressions like those presented in [9] and [10]<sup>2</sup>. The analysis yields analytical design equations that show the relation between the various design parameters.

<sup>1</sup>The Class-E topology given in [21] assumes zero switch parallel capacitor; which is only applicable for very dedicated technologies with very small  $R_{on}C_{out}$  product, where  $C_{out}$  is the switch (transistor) output capacitance.

<sup>2</sup>In [9] and [10], the switch on-resistance is assumed to be zero.

## II. ANALYSIS OF CLASS-E POWER AMPLIFIER

A single ended switching PA topology is given in Fig.1a. For correct input parameters and the circuit element values, the circuit properly operates as a Class-E PA by satisfying the following conditions (1) [9]:

$$V_C(2\pi/\omega) = 0 \quad \text{and} \quad \left. \frac{dV_C(t)}{dt} \right|_{t=2\pi/\omega} = 0 \quad (1)$$

A design set  $K = \{K_L, K_C, K_P, K_X\}$  (see Table-1) that relates circuit element values to operating conditions such as supply voltage, operating frequency and output power for the switching PA in Fig.1b can be derived. In [9], an analytical solution for  $K$  is given that enables infinitely many ideal Class-E realizations, to be selected by one parameter  $q = \frac{1}{\omega\sqrt{LC}}$ . In this paper, one more step is taken and the switch on-resistance  $R_{on}$  is included in the analysis. As it is shown (later) in this section the design set  $K$  can be expressed as a function of only two parameters  $q$  and  $m = \omega R_{on} C$  both of which are free design variables and can take any positive real value.

$$K_L = \frac{\omega L}{R}, \quad K_C = \omega C R, \quad K_P = \frac{P_{OUT} R}{V_{DD}^2}, \quad K_X = \frac{X}{R}$$

Table 1: Design Set  $K$  for Class-E PA<sup>3</sup>

As mentioned, the analytical solution in [9] is extended to cover Class-E PAs including  $R_{ON}$  in this paper.

### A. Circuit Description and Assumptions

The circuit model of the Class-E PA is given in Fig.1b. For the analysis and the derivations in this paper a number of assumptions are made:

- the only real power loss occurs on  $R$  and  $R_{on}$
- the switch (transistor) operates instantly with on-resistance ( $R_{on}$ ) and infinite off-resistance
- the loaded quality factor ( $Q_L$ ) of the series resonant circuit ( $L_0$  and  $C_0$ ) is high enough in order for the output current to be sinusoidal at the switching frequency
- the duty cycle is 50%

Fig.1c shows the switching behavior and the switch definition used: in the time interval  $0 \leq t < \pi/\omega$  the switch is closed and in  $\pi/\omega \leq t < 2\pi/\omega$  it is opened. This switching repeats itself with a period of  $2\pi/\omega$ .

### B. Circuit Analysis

In the analysis, the current into the load,  $I_R(t)$ , is assumed to be sinusoidal. Note that theoretically this occurs only for infinite  $Q_L$  of the series resonant network consisting of  $L_0$  and  $C_0$ . It is however a widely used assumption [8], [9], [12] that simplifies analysis considerably:

$$I_R(t) = I_R \sin(\omega t + \varphi) \quad (2)$$

In the time interval  $0 < t < \pi/\omega$ , the switch is closed. The KCL at the drain node can be written as:

$$I_L(t) - I_S(t) - I_C(t) + I_R(t) = 0 \quad (3)$$

<sup>3</sup>  $L_0$  and  $C_0$  seen in Fig.1 can be determined from the chosen loaded quality factor ( $Q_L = \omega_0 L_0 / R$ ) where  $\omega_0 = 1/\sqrt{L_0 C_0}$ .

Relation (3) can be arranged in the form of a linear, non-homogenous, second order differential equation

$$C \frac{d^2 V_{C_{on}}(t)}{dt^2} + \frac{1}{R_{on}} \frac{dV_{C_{on}}}{dt} - \frac{V_{DD} - V_{C_{on}}}{L} - \omega I_R \cos(\omega t + \varphi) = 0 \quad (4)$$

which has as solution

$$V_{C_{on}} = \frac{(q^4 \sin(\omega t + \varphi) m + (-q^2 + q^4) \cos(\omega t + \varphi)) p V_{DD}}{1 + (m^2 + 1) q^4 - 2 q^2} + V_{DD} + e^{a\omega t} C_{on2} + e^{b\omega t} C_{on1} \quad (5)$$

where,  $a = \frac{-1 + \sqrt{1 - 4q^2 m^2}}{2m}$ ,  $b = \frac{-1 - \sqrt{1 - 4q^2 m^2}}{2m}$  and  $p = \frac{\omega L I_R}{V_{DD}}$ .  $C_{on1}$  and  $C_{on2}$  follow from the continuity of the capacitor voltage ( $C$ ) and the inductor ( $L$ ) current at the switch-on moment.

In the time interval  $\pi/\omega < t < 2\pi/\omega$ , the switch is opened. Then, in the Class-E PA the current through capacitance  $C$  is

$$I_C(t) = \frac{1}{L} \int_{\pi/\omega}^t (V_{DD} - V_{C_{off}}(t)) dt + I_L \left( \frac{\pi}{\omega} \right) + I_R(t) \quad (6)$$

Relation (6) can be re-arranged in the form of a linear, nonhomogeneous, second-order differential equation

$$LC \frac{d^2 V_{C_{off}}(t)}{dt^2} + V_{C_{off}}(t) - V_{DD} - \omega L I_R \cos(\omega t + \varphi) = 0 \quad (7)$$

which has as solution

$$V_{C_{off}}(t) = C_{off1} \cos(q\omega t) + C_{off2} \sin(q\omega t) + V_{DD} - \frac{q^2}{1 - q^2} p V_{DD} \cos(\omega t + \varphi) \quad (8)$$

$C_{off1}$  and  $C_{off2}$  follow from the Class-E conditions (1).

It follows from (5) and (8) that  $V_{C_{on}}(t)$  and  $V_{C_{off}}(t)$  can be expressed in terms of  $V_{DD}$  and  $\omega$  hence be solved analytically only if  $\varphi$ ,  $q$ ,  $p$  and  $m$  are known. The derivation of the four parameters  $\varphi$ ,  $p$ ,  $q$  and  $m$  is the next step in the solution.

By using the continuity of the inductor current and the capacitor voltage at the switch turn-off moment we can derive two independent equations which can be shown to have the same format:

$$f_i(p, q, \varphi, m) = p \left( a_i(q, m) \cos(\varphi) + b_i(q, m) \sin(\varphi) \right) + c_i(q, m) = 0, \quad \text{where } i = 1, 2.$$

The variables  $p$  and  $\varphi$  can be solved by using  $f_1(p, q, \varphi, m)$  and  $f_2(p, q, \varphi, m)$  in terms of  $q$  and  $m$  as given in the appendix. Here,  $q$  and  $m$  are free variables that can mathematically take any positive real value.

### C. Design sets for Class-E operation

The results of the mathematical derivation of the solutions leading to Class-E operation can be used to derive an easy-to-use design procedure for Class-E PAs. Using the result of the derivation for  $p(q, m)$  and  $\varphi(q, m)$ , analytical expressions for the design set  $K = \{K_L, K_C, K_P, K_X\}$  can readily be derived.

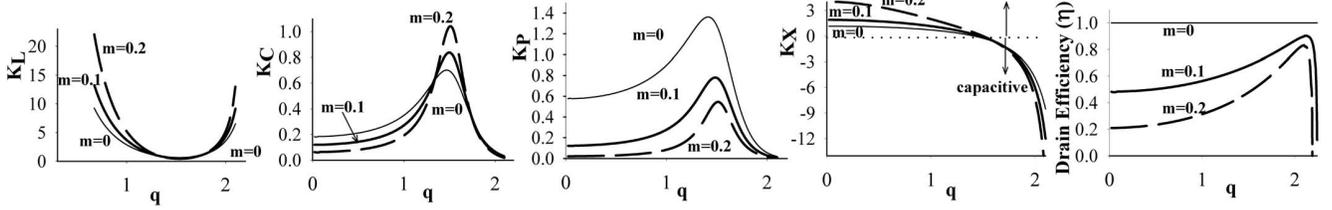


Fig. 2. (a) Design set  $K$  and drain efficiency ( $\eta$ ) as a function of  $q$  for  $m = 0, 0.1, 0.2$ .

$K_L$ : follows from the principle of power conservation:

$$I_R^2 R/2 + P_{switch} = I_0 V_{DD} \quad (9)$$

In this relation,  $I_0$  is the average supply current:

$$I_0 = \frac{\omega}{2\pi R_{on}} \int_0^{\pi/\omega} V_{C_{on}}(t) dt \quad (10)$$

and,

$$P_{switch} = \frac{\omega}{2\pi R_{on}} \int_0^{\frac{\pi}{\omega}} (V_{C_{on}}(t))^2 dt$$

Substitution of (10) and  $p$  in (9) yields

$$K_L(q, m) = \frac{-(pV_{DD}q)^2 m\pi}{\omega \int_0^{\frac{\pi}{\omega}} (V_{C_{on}}(t))^2 - V_{DD}V_{C_{on}}(t) dt}$$

Since  $p$  and  $\varphi$  are all functions of  $q$  and  $m$ ,  $K_L(q)$  is a function of e.g. only  $q$  and  $m$ .

$K_C$ : follows directly from the definition of  $q$  and  $K_L$ :

$$K_C(q, m) = \frac{1}{q^2 K_L(q, m)}$$

$K_P$ : can easily be found as a function of  $q$  and  $m$  by using  $I_R = \sqrt{2P_{OUT}/R}$  and the definition of  $p$ :

$$K_P(q, m) = p(q, m)^2 / (2K_L(q, m)^2)$$

$K_X$ : can be derived using two fundamental quadrature Fourier components of  $V_C(t)$ .

$$V_R = \int_0^{\frac{\pi}{\omega}} \frac{V_{C_{on}}(t)}{\pi} \sin(\omega t + \varphi) dt + \int_{\frac{\pi}{\omega}}^{\frac{2\pi}{\omega}} \frac{V_{C_{off}}(t)}{\pi} \sin(\omega t + \varphi) dt$$

$$V_X = \int_0^{\frac{\pi}{\omega}} \frac{V_{C_{on}}(t)}{\pi} \cos(\omega t + \varphi) dt + \int_{\frac{\pi}{\omega}}^{\frac{2\pi}{\omega}} \frac{V_{C_{off}}(t)}{\pi} \cos(\omega t + \varphi) dt$$

$$K_X(q, m) = V_X / V_R$$

**Drain efficiency( $\eta$ ):** can be derived as a function of  $q$  and  $m$ .

$$\eta(q, m) = 1 - \frac{P_{switch}}{V_{DD}I_0} = 1 - \frac{\int_0^{\frac{\pi}{\omega}} (V_{C_{on}}(t))^2 dt}{V_{DD} \int_0^{\frac{\pi}{\omega}} V_{C_{on}}(t) dt}$$

We verified the given design equations in this paper by simulating the model given in Fig.1b by transient and pss

| Design Details                                      | RF-choke ( $q=0$ )       | finite ( $q=1.47$ )    | finite ( $q=1.78$ )    |
|---|--------------------------|------------------------|------------------------|
| $f$ (GHz), $V_{DD}$ (V), $Q_L$                      | 2.4, 0.5, 10             | 2.4, 0.5, 10           | 2.4, 0.5, 10           |
| $P_{OUT}/P_{DC}$ (mW)                               | 10.6/22.2                | 11.8/17.0              | 12.1/15.2              |
| <b>m, Drain Efficiency(<math>\eta</math>)</b>       | <b>0.1, 47.7%</b>        | <b>0.1, 69.4%</b>      | <b>0.1, 79.6%</b>      |
| <b>L, <math>L_X</math>(nH), <math>C</math>(pF)</b>  | <b>20.29, 0.38, 2.59</b> | <b>0.72, 0, 2.82</b>   | <b>0.4, -, 3.48</b>    |
| <b>R(<math>\Omega</math>), <math>C_X</math>(nF)</b> | <b>3.06, -</b>           | <b>19.47, -</b>        | <b>5.06, 6.88</b>      |
| <b>(W(u)/L(u)), <math>K_L</math></b>                | <b>(297/0.1), 100</b>    | <b>(323/0.1), 0.56</b> | <b>(398/0.1), 1.19</b> |
| $K_C, K_P, K_X$                                     | 0.12, 0.12, 1.89         | 0.83, 0.78, 0          | 0.27, 0.20, -1.90      |
| Technology  | 90nm CMOS                | 90nm CMOS              | 90nm CMOS              |

Table 2: Comparison and design summary of the three Class-E PA designs for  $m = 0.1$  and  $q = 0, 1.47, 1.78$  in CMOS 90nm transistor technology

(periodic steady state) simulations in spectre (cadence). Very good agreement in the waveforms and the drain efficiency are observed between the simulations and the theory with a discrepancy of  $\approx 2\%$ ; attributed to the finite value of  $Q_L = 10$ .

In theory,  $q$  can take any positive real number however, as it is seen in Fig.2  $K_C, K_P$  and  $\eta$  approach to zero for  $q > 2$ . Therefore, the useful range of the analytical solution can be assumed to be restricted to  $0 < q < 2$  in Class-E PA designs. Similarly, as  $m$  increases  $K_P$  and  $\eta$  drops as observed in Fig.2; indicating the degradation in Class-E PA performance.

### III. DESIGN EXAMPLES AND DISCUSSION

The analytical design equations reveal very important properties of the Class-E PAs. For example, we can express  $m \approx \beta\omega$  where  $\beta = R_{on}C_{out}$ .  $\beta$  is a characteristic property of the transistor technology used as a switch in Class-E PA design<sup>4</sup>. For a certain operation frequency and transistor technology  $m$  has a certain value. As it is seen in Fig.2, there is a maximum efficiency level that could be achieved for a given  $m$ ; showing that the transistor technology and the frequency of operation sets an upper limit for  $\eta$  of a Class-E PA.

The chosen value of  $q$  considerably influence  $\eta$  as observed from Fig.2 and the simulation results given in Table-2. We designed three Class-E PAs for an output power of 10 mW<sup>5</sup>. Finite dc-feed Class-E PA( $q=1.78$ ) has  $\eta$  that is  $\approx 30\%$  higher than RF-coke Class-E PA( $q = 0$ ); indicating how much  $\eta$  can be influenced by the chosen design equations.

<sup>4</sup>In order to minimize  $R_{on}$ , maximum possible transistor size can be chosen for which transistor output capacitance  $C_{out} = C$ .

<sup>5</sup>Slightly higher output power than 10 mW is attributed mostly to deviation of transistor characteristic from an ideal switch behavior at high frequency.

Although the Class-E PA( $q = 1.47$ ) has lower  $\eta$  than the Class-E PA( $q = 1.78$ ) it's load resistance( $R$ ) is  $\approx 4$  times higher than that of the Class-E PA( $q = 1.78$ ); which is very advantageous for low supply voltage - high output power Class-E amplifiers<sup>6</sup>

The Class-E PA( $q = 1.78$ ) can be used for low power applications (e.g. wireless sensors) where the transmit power levels are low  $\approx (1-3)mW$  [22] and high efficiency is crucial. If the Class-E PA( $q = 1.78$ ) is designed for an output power of  $1 mW$ , it needs  $R \approx 50 \Omega$ ; meaning that a matching network between the PA and the antenna is not needed.

#### IV. CONCLUSION

In this paper, we present a time domain analysis and closed form analytical design equations for Class-E power amplifiers with *finite dc-feed inductance* and *non-zero switch on-resistance*. Important outcomes of the analysis include:

- 1) Class-E conditions (e.g zero voltage and zero slope) can be satisfied in the presence of the switch on-resistance.
- 2) Drain efficiency ( $\eta$ ) for Class-E PAs is upper limited by the transistor technology and the operation frequency.
- 3) Using a finite dc-feed inductance instead of an RF-choke in Class-E PAs increases  $\eta$ . Depending on the transistor technology and the operation frequency the increase in  $\eta$  can be as high as  $\approx 30\%$ .

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<sup>6</sup>In order to obtain high output power from low supply voltage Class-E PAs a matching network that steps down  $50 \Omega$  antenna impedance to low impedance values is used. In the absence of high Q inductors the matching network can be very lossy for high transformation ratios.

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#### APPENDIX I

In this section the solution for  $p$  and  $\varphi$  in terms of  $q$  and  $m$  are given<sup>7</sup>.

$$p = \frac{\sqrt{(g_1 h_3 - g_3 h_1)^2 + (h_2 g_3 - h_3 g_2)^2}}{-g_1 h_2 + g_2 h_1}, \varphi = \arctan(h_2 g_3 - h_3 g_2, g_1 h_3 - g_3 h_1)$$

$$g_1 = \frac{-e^{a\pi} (A + bm^2) + e^{b\pi} (A + am^2)}{B(-b+a)} - \frac{q \sin(q\pi)}{q^2 - 1} + \frac{mq^2}{B}$$

$$g_2 = -\frac{(\cos(q\pi) + 1)q^2}{q^2 - 1} + \frac{m^2 q^2 (q - 1)(q + 1)}{B} + \frac{-e^{a\pi} (Ab - mq^2) + e^{b\pi} (Aa - mq^2)}{B(-b+a)}$$

$$g_3 = \frac{e^{b\pi} a - e^{a\pi} b}{-b+a} - \cos(q\pi)$$

$$h_1 = \frac{m^3 q^2 (q - 1)(q + 1)}{B} - \frac{q(m \cos(q\pi)q + \sin(q\pi) + mq)}{q^2 - 1} + m \left( \frac{ae^{a\pi} (A + bm^2)}{B(-b+a)} - \frac{be^{b\pi} (A + am^2)}{B(-b+a)} \right)$$

$$h_2 = -\frac{m^2 q^2}{B} + \frac{q^2 (m \sin(q\pi)q - \cos(q\pi) - 1)}{q^2 - 1} + m \left( \frac{ae^{a\pi} (Ab - mq^2)}{B(-b+a)} - \frac{be^{b\pi} (Aa - mq^2)}{B(-b+a)} \right)$$

$$h_3 = -\cos(q\pi) + m \sin(q\pi)q + m \left( \frac{ae^{a\pi} b}{-b+a} - \frac{be^{b\pi} a}{-b+a} \right) + 1$$

$$A = (q^4 - q^2) m^2 \text{ and } B = 1 + m^2 q^4 - 2m^2 q^2 + m^2$$

<sup>7</sup>Two roots exist for  $p$  and  $\varphi$ . The second root is  $p' = -p$  and  $\varphi' = \arctan(-h_2 g_3 + h_3 g_2, -g_1 h_3 + g_3 h_1)$ . Both roots result in the same K.