

Transport Properties of Multifilamentary Ag-Sheathed Bi-2223 Tapes under the Influence of Strain

Takanobu Kiss, Hans van Eck, Bennie ten Haken, and Herman H.J. ten Kate

Abstract—Current-voltage (I - V) characteristics in multifilamentary Ag/Bi2223 tapes are investigated as a function of mechanical strain. As is well known, the critical current, I_c , in axially elongated tape remains almost constant up to a strain around 0.5%, then is followed by a sharp reduction. However, for larger elongations, a long tail in the I_c -strain curve is observed, i.e., around 20% of the initial I_c still remains even at 0.8% strain. The irreversible I_c reduction indicates that the degradation comes from the break-down of superconducting filaments. However, it is observed that the rupture risk probability reduces as the strain is increased in the long tail. This anomaly suggests that the measured strain of the whole tape is not identical to that of the HTS filaments inside the tape. We propose a model to describe the mechanical properties of the tape. It is shown that 1) the break-down probability of the filaments is well described by the Weibull function if we calculate the influence of shearing between the superconducting filaments and the surrounding Ag sheath, 2) the I_c -strain properties can be described accurately by the model, 3) transport I - V characteristics can also be described simultaneously as a function of strain.

Index Terms—Bi-2223 tape, tensile strain, critical current, transport properties, high-temperature superconductors.

I. INTRODUCTION

KNOWLEDGE of the strain properties of superconducting tapes are essential for practical application. The typical mechanical feature of HTS multifilamentary tapes is that brittle ceramic filaments are surrounded by soft metal sheath such as Ag or Ag-alloy. Consequently, the mechanical response against strain is complicated, and then the strain dependence of the critical current, I_c , is very much different from that of low temperature superconductors (LTS). It was shown that I_c in conventional LTS tape was reduced reversible as strain, ϵ , was increased [1],[2]. The change of I_c is thought to originate from the variation of the upper critical magnetic field, B_{c2} . This idea is supported by the scaling behavior of pinning force density under the influence of strain [1],[2]. In HTS tapes, however, it has almost always been

observed so far that 1) the reduction of I_c is irreversible and 2) the reduction ratio of I_c is independent of magnetic field, B . These results suggest that the I_c reduction in HTS tapes mainly comes from the mechanical break-down of superconducting filaments in the tape [2].

The typical response for the axially elongated tape is as follows. The value of the initial I_c is hardly reduced up to a strain around 0.4%. Then it drops sharply when the strain exceeds a critical value, ϵ_c . It was reported [2] that the threshold is determined by the compressive strain in the HTS filaments remaining after the heat treatment during the fabrication process. When the strain is increased to be much larger than the critical value, the reduction of I_c shows a tendency to be saturated. In many cases, the value of I_c still retains 20% of the initial value even when the strain is as large as 0.8%.

However, the strain we can measure is the apparent value of the whole tape. It is hardly possible to measure the strain of each filament inside the tape directly. Taking into account the fact that the HTS tapes are composites consisting of elements having quite different mechanical properties, we can easily imagine that the apparent strain could be different from that of the HTS filaments. Nevertheless, only a few studies have been carried out to clarify the detailed mechanical properties in HTS tapes at the moment. Moreover, in spite of the significant number of studies on the strain effect, most of them are concentrated on the influence on I_c , whereas the performance of the HTS-based devices depends strongly on the sharpness of the transition in transport electric field (E)-vs.-current density (J) curves. It is necessary to investigate the influence on transport E - J curves as well.

In this study, we investigate the influence of tensile stress on the transport E - J characteristics in Bi-2223 multifilamentary tapes over a wide range of strain. We propose a model to describe the mechanical properties as well as transport properties in the tape. The comparison between the model and the measured results will be discussed.

II. EXPERIMENT

A schematic diagram of the instruments for the measurements is shown in Fig. 1. The Bi-2223 tape sample was soldered on the U-shaped spring stage made of brass. The strain is applied by elongating the spring in the axial direction. The amount of the strain is monitored by strain gauges mounted on the stage [2]. In our experiment we defined the strain value from as-cooled condition in liquid nitrogen.

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Namely, we ignored the off-set strain value originated from cooling. Recently, Kitaguchi et al. have reported that about 0.2% compressive strain will be introduced in the tape at liquid nitrogen temperature because of the difference of thermal contracts between Ag sheathed HTS tape and brass stage [4]. If we take into account this off-set value, the strain value will be reduced about 0.2%. Applying the tensile strain systematically, we measured extended E - J curves of the tape by the four probe method. The distance between the voltage taps was 1 cm.

III. RESULTS AND DISCUSSION

A. I_c -strain properties

In Fig. 2, we show the strain dependence of I_c , which is determined by the $1 \mu\text{V}/\text{cm}$ criterion. The value of I_c was almost constant up to the strain value of 0.5%, then followed by a sharp reduction. However, in the large strain region we can see a long tail. Namely, the I_c is still 20% of the initial value even when the strain is as large as 0.8%. The reduction of I_c did not recover if we reduced the strain. Also, the strain dependence did not depend on magnetic field. These results suggest that the I_c degradation originates from the mechanical break-down of the filaments. Therefore, it would be reasonable to assume that the reduction ratio of I_c is approximately proportional to the rupture probability, G , of the filaments. That is, $G(\epsilon) = I_c(\epsilon) / I_c(0)$.

We can obtain the rupture risk probability as a function of ϵ from the result of Fig. 2, i.e., $(dG/d\epsilon)/(1-G)$. The result is shown in Fig. 3. Note that the rupture risk probability for a small increment of ϵ increases rapidly at the threshold, however, it is reduced again as ϵ further increases. Namely, in the long tail region, the rupture risk probability becomes smaller and smaller as the strain is increased. This anomaly strongly suggests that the measured ϵ is not identical to the actual strain in the filament because of a shearing between the remained filaments and Ag sheath as the break-down occurs in some part of the filaments.

B. Modeling

In this study, we elongated the sample by expanding the spring stage in the axial direction. We modeled, therefore, the mechanical response of the tape by taking into account the one-dimensional axial elongation by a spring network model as shown in Fig. 4. For simplicity, only the right half side of the stage is shown. The network consists of two elements, i.e., the coil spring, which represents the elastic interaction of the HTS filaments, and a flat spring, which represents shearing between the filaments and the sheath. The spring constants of those two springs are k_1 and k_2 per unit length, respectively. It can be seen that the strain in the filament, ϵ_1 , is smaller than the applied strain, ϵ_{eff} , due to the shearing, ϵ_2 . Moreover, the rupture probability of the filament, G , is assumed to be given by the well-known Weibull function. When the strain, ϵ , is smaller than the critical value, ϵ_c , prestrain in the filaments, due to thermal contraction, is released. Therefore, G is

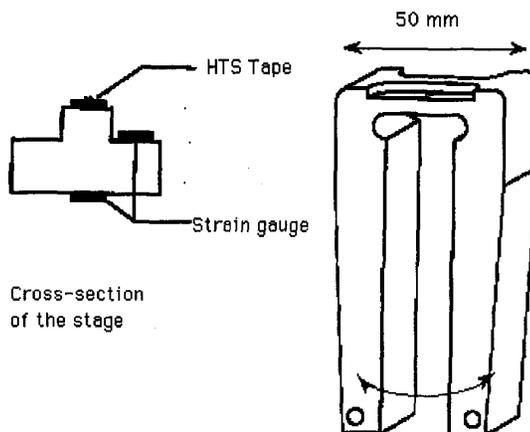


Fig. 1. Schematic diagram of the equipment which was used to apply strain to the HTS tape [2].

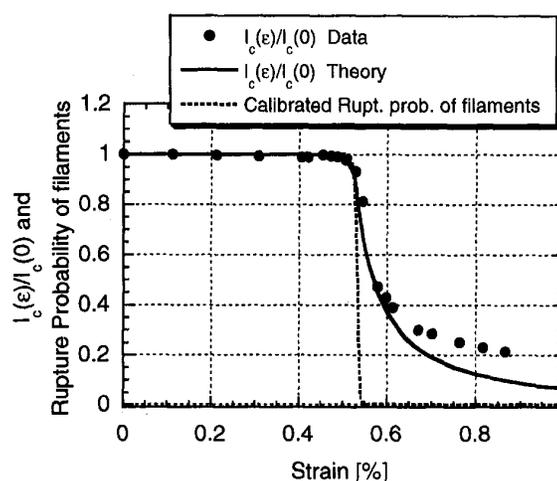


Fig. 2. I_c -vs.-apparent strain. The initial value of I_c was 30 A. The dots are measured results whereas the solid line is a calculation based on our model. The dotted line indicates the rupture probability of the filaments described by the Weibull function, (1.a) and (1.b), where the strain is calculated in the filaments. The numerical parameters are as follows: $\epsilon_c=0.39$, $\epsilon_0=0.1$, $\hat{m}=20$ and $k=0.17$.

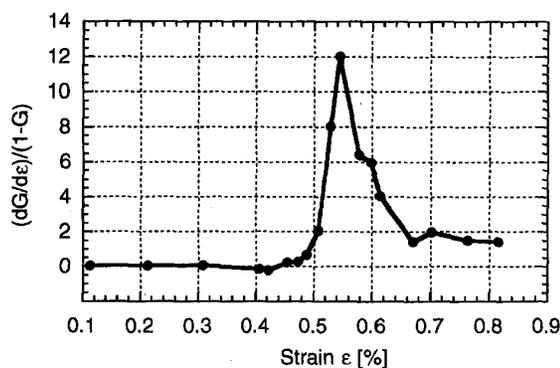


Fig. 3. The anomaly of the rupture risk probability, $(dG/d\epsilon)/(1-G)$, obtained from the measured I_c - ϵ properties shown in Fig. 2 where $G(\epsilon)=I_c(\epsilon)/I_c(0)$.

assumed to be given by the following equation:

$$G(\varepsilon) = 1 - \exp\left[-\left(\frac{\varepsilon - \varepsilon_c}{\varepsilon_0}\right)^{\hat{m}}\right] \quad \text{for } \varepsilon \geq \varepsilon_c \quad (1.a)$$

$$= 0 \quad \text{for } 0 \leq \varepsilon < \varepsilon_c \quad (1.b)$$

where ε_0 is a scale parameter and \hat{m} is a numerical constant describing the mode of destruction. The influence of the filament destruction in some parts of the cross-section will be reflected effectively as a variation of the shearing constant in the one-dimensional model. As the filament destruction progresses, the stress force should be sustained by the remaining filaments and sheath. Therefore, the effective shearing constant becomes smaller as the rupture probability increases. We assume that the ratio between k_1 and k_2 is a function of ε , then it is given by the following equation:

$$\frac{k_1(\varepsilon)}{k_2(\varepsilon)} = k \frac{G(\varepsilon)}{1 - G(\varepsilon)}, \quad (2)$$

where k is a parameter characterizing the mechanical coupling strength between the filaments and the sheath. It can be expected that the value of k will be small when the tape has a dense structure.

In order to clarify the relationship between the apparent strain and the real strain in the filaments, we analyze the properties of the model shown in Fig. 4. This problem can be transformed to make clear the relationship between the effective spring constant of the network and k_1 . Because the relationship between stress and strain is the same as between voltage and current in a conductor, we can replace the mechanical model with the distributed resistance network model in an analogous way as shown in Fig. 5. ρ_1 is the resistance per unit length, which corresponds to k_1 , whereas $1/\rho_2$ is the leakage conductance, which corresponds to k_2 . Consequently, we will obtain the relationship between ε_1 and ε_{eff} if we obtain the relationship between effective resistance, ρ_{eff} , of the resistance network and ρ_1 . Namely,

$$\frac{\varepsilon_1}{\varepsilon_{eff}} = \frac{k_{eff}}{k_1} = \frac{\rho_{eff}}{\rho_1} \quad (3)$$

Voltage, V , and current, I , in the distributed circuit are given by the following differential equations:

$$dV = -I \rho_1 dx, \quad (4.a)$$

$$dI = -\frac{1}{\rho_2} V dx, \quad (4.b)$$

then

$$\frac{d^2V}{dx^2} = \frac{\rho_1}{\rho_2} V, \quad (4.c)$$

where x indicates the distance along the tape. Solving the differential equation (4.c) with the boundary conditions:

$$V = V_i \text{ and } I = I_i, \quad \text{for } x = 0 \quad (5.a)$$

$$V = 0, \quad \text{for } x = 1 \quad (5.b)$$

we obtain the effective resistance, ρ_{eff} , for the unit length as

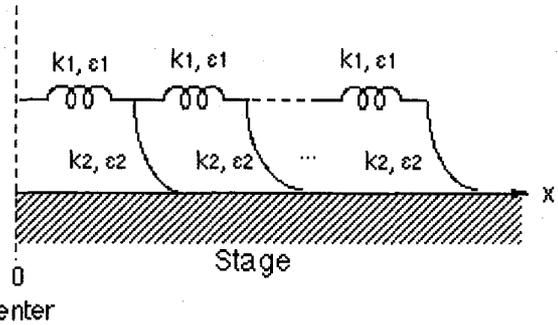


Fig. 4. Spring network model that takes into account the shearing between the HTS filaments and outer sheath.

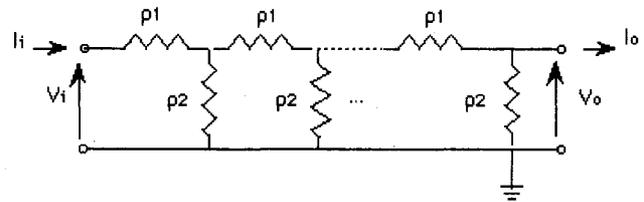


Fig. 5. Equivalent electric circuit model.

$$\rho_{eff} \equiv \frac{V_i}{I_i} = \sqrt{\rho_1 \rho_2} \tanh\left(\sqrt{\frac{\rho_1}{\rho_2}}\right). \quad (6)$$

Therefore, the real strain in the filaments, ε_1 , can be obtained from the measured strain, ε_{eff} , by the following relationship:

$$\varepsilon_{eff} = \varepsilon_1 \sqrt{\frac{k G(\varepsilon_1)}{1 - G(\varepsilon_1)}} \coth\left(\sqrt{\frac{k G(\varepsilon_1)}{1 - G(\varepsilon_1)}}\right). \quad (7)$$

C. Transport E - J curves under the influence of tensile strain

In this section, we calculate the transport E - J characteristics by expanding the mechanical model described in the preceding section. We confirmed that the I_c reduction ratio by the strain does not depend on magnetic field. Therefore, we assume that the pinning properties are not varied by the strain in the present experiment. Namely, the variation of I_c comes only from the change of geometrical cross section area of the tape due to cracking.

The region where the filaments are destroyed reduces the effective cross-section area as schematically shown in Fig. 6. Due to the reduction of cross-section area, the current density in the remaining filaments is increased inversely proportional to $1-G$. As a result, the filament resistance in the crack region, ρ_c , is enhanced locally, and some part of the current will leak to the surrounding sheath. The relationship between the effective resistance and the filament resistance has already been given by (6) as described in the preceding section. Moreover, the length of the destroyed region per unit length will be given by $\varepsilon_{eff} - \varepsilon_1$. Therefore, the total resistance per unit length will be given by a series connection of undestroyed region and the destroyed region.

$$\rho_{eff} = \sqrt{\rho_1 \rho_2} \tanh\left(\sqrt{\frac{\rho_1}{\rho_2}}\right) + \sqrt{\rho_c \rho_2} \tanh\left((\varepsilon_{eff} - \varepsilon_1) \sqrt{\frac{\rho_c}{\rho_2}}\right), \quad (8)$$

$$\text{where } \rho_1 = \frac{E(I/(aS))}{l} \text{ and } \rho_c = \frac{E(I/[aS(1-G)])}{l},$$

$S(= 8.5 \times 10^{-7} \text{ m}^2)$ is the cross-section area of the tape, $a(=0.3)$ is the filling factor of the HTS filaments, and ρ_2 is the leakage resistance to the Ag sheath per unit length. Note that we assume that the essential $E(J)$ characteristics in the remaining filaments are the same as the initial characteristics.

We estimated the value of ρ_2 based on the following consideration. In the case when the resistivity in the HTS filament is equal to that of the sheath, the apparent resistivity estimated by (6) is also equal to that of the sheath. Using this condition, we evaluate the value of ρ_2 . That is

$$\rho_2 \equiv \frac{a}{S} \rho_{Ag}, \quad (9)$$

where ρ_{Ag} is the resistivity in the sheath. We obtained the value $\rho_{Ag} = 3.3 \times 10^{-7} \Omega\text{cm}$ at 77.3 K by measuring the linear resistance of the tape after breaking down the HTS filament mechanically. Using this value, we can estimate ρ_2 as 10 $\mu\Omega/\text{cm}$ approximately in the present sample.

We have already proposed a method to describe transport E - J characteristics in HTS based on a percolation model [3]

$$E(J) = \frac{\rho_{FF}}{m+1} J \left(\frac{J}{J_0} \right)^m \left\{ 1 - \frac{J_{cm}}{J} \right\}^{m+1}, \quad \text{for } B \leq B_{GL}, J \geq J_{cm} \quad (10.a)$$

$$= \frac{\rho_{FF}}{m+1} |J_{cm}| \left(\frac{|J_{cm}|}{J_0} \right)^m \left\{ \left(1 + \frac{J}{|J_{cm}|} \right)^{m+1} - 1 \right\}, \quad \text{for } B > B_{GL}, J \geq J_{cm} \quad (10.b)$$

$$= 0 \quad \text{for } J < J_{cm} \quad (10.c)$$

where J_{cm} is the minimum value of the critical current density in the statistic J_c distribution, J_0 is the scale parameter indicating the width of the J_c distribution, m is a parameter determining the shape of the J_c distribution, ρ_{FF} is the flux flow resistivity in uniform flux flow, and B_{GL} is the transition field where $J_{cm}=0$ [3]. The initial E - J characteristic in the present experiment can be described by this model well with the numerical parameters: $J_{cm}=9.48 \times 10^7 \text{ A/m}^2$, $J_0=2.80 \times 10^8 \text{ A/m}^2$, $m=3.5$ and $\rho_{FF}=10 \mu\Omega\text{cm}$. Then, we finally obtain the strain dependence of the E - J characteristics.

Comparison between the theory and the measured results is shown in Fig. 7. It can be seen that the model describes precisely the experimental results except in the very large strain region. The calculation results describe the detailed features of the experimental results: 1) before the sharp reduction of I_c , the degradation occurs first in the lower electric field region, 2) the variation of n value can be described as well. The reduction of I_c , determined using 1 $\mu\text{V}/\text{cm}$ criterion, is also shown by the solid line in Fig. 2. In the same figure, we plot the rupture probability of the filaments calculated by (1.a), (1.b) and (7) with the numerical parameters: $\epsilon_c=0.39$, $\epsilon_0=0.1$, $\hat{m}=20$, and $k=0.17$. It can be seen that if we consider the influence of the shearing, the filaments break sharply when the applied strain exceeds the critical value. This is quite reasonable if we take into account

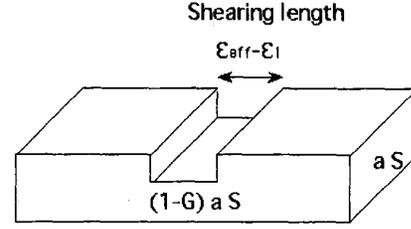


Fig. 6. In the ruptured region, the effective cross-section area is reduced inversely proportional to $1-G$. The length of the narrowed region is assumed to be equal to the shearing length.

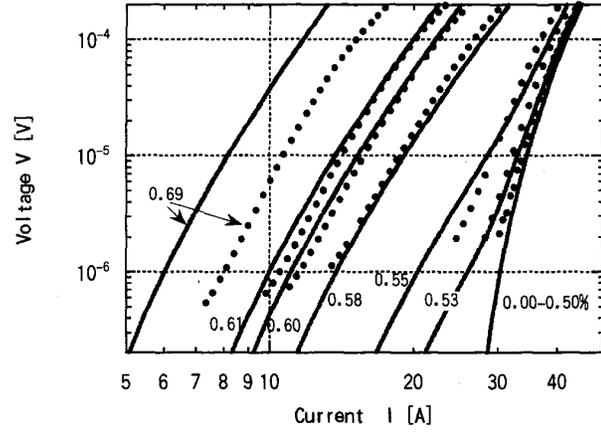


Fig. 7. Transport E - J characteristics as a function of strain. The dots are measured results while the solid lines are the results obtained by the present model. The numbers beside the lines indicate the value of tensile strain.

the brittle properties of HTS filaments.

These results indicate that the proposed model can describe the mechanical properties as well as the transport current properties of the HTS tape.

IV. CONCLUSION

We proposed a model to describe the mechanical properties of multifilamentary HTS tape. It is shown that 1) the breakdown probability of the filaments is well described by the Weibull function if we consider the influence of shearing, 2) the I_c -strain properties can be described accurately by the model, 3) transport I - V characteristics can also be described simultaneously as a function of strain.

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