Flowdrilling: a Preliminary Analysis of a New Bush-Making Operation
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Flowdrilling is a bush-making operation applied to thin walled products for joint engagement. Fastenings exhibit mechanical properties which depend largely on the shear strength of the parent material and the area of engagement. Flowdrilling is specifically designed to increase the latter.

Contrary to conventional drilling, in Flow-drilling there is no material removal but a displacement of material. The bush is formed from the parent material which is subjected to friction heating, but at the end the bush material has a finer structure because of the occurrence of dynamic recrystallization.

Flow-drilling is a single cycle operation suited for automated manufacturing production. Because there is no need for inspection, Flow-drilling can immediately be followed by thread roll-forming. There is no need for the use of material sockets: the parent material is being used.

Figure 1A shows the typical shape of a flow-drilling tool, having a specially shaped conical nose. In general the shape of the flow-drill can be divided into 5 sections:
1. The tip
2. The conical part (top-angle about 35°)
3. The calibration (cylindric) part
4. The collar
5. The shank

Figure 1A: Typical shape of a flow-drilling tool.

The presently available tools are made of cemented carbide (P25-P35) covering diameters from 3 mm to about 50 mm. Both the conical and the calibration part are provided with 1 or 4 facets (see fig. 1A, cross-section AA) to promote local friction heating while preventing sticking. Tools above 10 mm diameter are provided with a boring (0.4mm) to prevent rupture by thermo-shock.

Flow-drilling is an operation controlled by friction heating. Starting from an initial indentation, and under the influence of a constant axial pressure, the heated metal of the workpiece is extruded both upwards and downwards in the ratio of about 45% to 60% respectively. The height of the so-formed bush measures 2.5 to 3 times the original thickness of the material. Due to local friction heating of the workpiece, the operation can be performed with a relatively small axial pressure, so that there is no need for special measures to support blind sections. Flow-drilling requires the use of a high-temperature resistant lubricant, (MoyniteMTO and HTP) sparingly applied to the tool to prevent sticking, which is detrimental to surface quality and tool life (vibrations).

The main area of application is in the manufacture of manifolds for air, gas or liquid and direct fastenings in metal furniture, domestic products and in the electric and electronic industry. A flow-drilled bush can be used as a seal for plain bearings in a wide range of machinery, and even can itself act as a bearing surface.

Flow-drilling can be applied to a wide variety of materials like different carbon steels, stainless steel, copper, brass and aluminium. Difficulties arise for strong pre-strainhardened qualities, which, in particular in the case of aluminium, results in a bad quality of the bush.

The advantages of flow-drilling compared to other methods of making fixing bushes are the following [4][6]:
- Flow-drilling is a single cycle operation suited for automated manufacturing production.
- Because there is no need for inspection, flow-drilling can immediately be followed by thread roll-forming.
- There is no need for the use of material sockets: the parent material is being used.
- Crevice and dissimilar-metal corrosion do not occur.
- Using a collar on the tool results in a flat mounting face on the bush. In the case of threaded bushes there is no need for a washer to get a gas tight connection.
- It is possible to produce bushes in blind sections because there is no need for support at the rear.
- Threaded joints and soldered, brazed or adhered connections are of a high integrity.
- There are no disturbances caused by chips (like in normal drilling).
- Thinner walled materials can be used when compared with direct drill/tap operations.

The economic advantages of flow-drilling depend on a variety of considerations like capital equipment costs, production times and labour involvement.
Three common available types of flow-drills are given in Figure 2. Type A represents the standard type. Flow-drills for the bushes B and D are provided with cutting edges on the collar which (partly) remove the upwards extruded part of the bush. In the case of D the bush has been counterbored. The flow-drill of the type C has a long cylindrical section to get a bush as high as possible.

The required spindle-power measures approximately four times that needed for conventional drilling. This counts for the usually applied (max.) surface speed of about 1.5 m/s. The tool holder must have a means for heat dissipation to prevent overheating of the spindle-bearings. When a pressure-controlled feed drive is used, the need for feed-rate control makes a hydraulic damped pneumatic feed-drive mechanism essential. Because of the fact that the start of the process is difficult in conventional flow-drill, a flow-drilling machine needs a stable spindle. Bending moments on the flow-drill must be avoided because of the brittle nature of the tool material (no significant radial forces on the tool tip).

The outer diameter of the bush is not constant and varies significantly with the different directions. This effect is coming into account when the surrounding area of the bush becomes asymmetric within a radius of four or five times the diameter.

In the case of a threaded bush the strength of the connection is even better than that required according to DIN-standards [4].

DESCRIPTION OF THE FLOW-DRILLING PROCESS

General.

In Figure 1A a standard shape flow-drill is given. Using this type of flow-drill, the bush-making operation can be considered to consist of three phases, respectively:

1. The start-up: from the first contact of the tip of the flow-drill with the workpiece up to that position where the travelled distance in axial direction is equal to the material thickness (z = md = lc1).

2. The extrusion phase: from z = md up to that position where the displacement z equals 1 + 1 + h (bush length).


Figure 3 gives a survey of the different variables involved.

The different variables are arranged as follows:

I. Independent variables

a. Workpiece and tool parameters
   - Material properties of tool and workpiece
   - Thickness of the workpiece material md [mm]
   - Diameter of the tool [mm]

b. Free (adjustable) variables
   - Feed force/feed velocity \( F_z/V_z \) [N]/[m/s]
   - Rotation speed \( \omega \) [rad/s]
   - Surface speed \( V_z \) [m/s]
   - Lubricant

II. Dependent variables

a. Process:
   - Feed velocity/feed force \( V_z/F_z \) [m/s]/[N]
   - Apparent Coefficient of Friction \( \mu_{app} \) [-]
   - Driving moment \( M_{d} \) [Nm]
   - Contact temperature (tool/workpiece) \( T_{T} [\degree C] \)
   - (Specific) Energy \( W_{sp} \) [J/kg]
   - (Specific) Power \( W_{sp} \) [W/kg]
   - Axial forces \( F_z \) [N]

b. Product:
   - Inner diameter of the bush \( D_b \) [mm]
   - Wall thickness of the bush \( t_b \) [mm]
   - Total height (length) of the bush \( h \) [mm]
   - Total height (length) of the down-ward bush \( h_2 \) [mm]
   - Total height (length) of the up-ward bush \( h_4 \) [mm]

Measurements are carried out using a specially designed flow-drilling machine supplied with a hydraulic damped pneumatic feed-drive mechanism. In this case the feed force is adjustable.

The presently reported results concern:

Diameters \( D_b \): 9 12 16 mm

Material thickness \( m_d \): 2 3 4 5 mm

Kinds of material: Mild steel, Alfa-brass, Stainless steel

(C20) (60Si3,30Si) (C18,411,1.5)

The experimental program has been arranged as given below:

\[ m_d = m_d_1 = m_d_2 = m_d_3 \]

a. Mild steel \( D_b = 9, 12, 16 \)

b. Alfa-brass \( D_b = 9, 12, 16 \)

c. Stainless steel \( D_b = 9, 12, 16 \)

Figure 4: Feed force \( F_z \) and feed velocity \( V_z \) vs. t for the start-up and the extrusion phase only.
At the start of the process, the feed force is built up in a very short period of time. However, both the contact surface and the surface speed between flow-drill and workpiece are very small. Despite a high contact pressure, only a low amount of energy is dissipated. Below certain minimum values of \( F_c \) and \( \phi \) the process will not start. The ratio of generated and conducted heat is too low. After the start-up \(( s = md)\) the feed velocity increases significantly as a result of an increased heat generation caused by the increasing surface speed. This causes the actual feed force to decrease after the start-up because the hydraulic damper becomes more active. During the extrusion phase the feed force increases somewhat \((\approx 5\%)\). This again is a result of the changing velocity of the tool in \( z \)-direction. When the extrusion phase is completed \(( s = l = h)\) the actual flow-drilling is over. The contact temperature decreases and the bush tends to shrink, so the rotating flow-drill is being clamped and, in a way, the process is started-up again. This effect continues to work periodically for a while, during which period the surrounding material cools and shrinks. The increase of the feed force causes significant radial forces by increasing surface speed. This again is a result of the changing velocity of the tool in \( z \)-direction. When the extrusion phase is completed, the moment of friction increases linearly with the position and thus with the diameter of the tool. This obviously indicates that the active areas on the facets of the tool remain equal over the length of the cone.

![Figure 5: Friction moment \( M_f \) and Contact Temperature \( T_c \) vs. \( z \) for the start-up and the extrusion phase only.](image)

After the extrusion phase, initially the moment of friction decreases very slowly. But shortly after that, during calibration, it starts oscillating around a certain value, this coinciding with temperature and sound effects. The measurement of the contact temperature is difficult since the temperature gradient \( \Delta T / \Delta z > 300 \, ^\circ \text{C} / \text{sec} \) and \( \Delta T / \Delta z > 200 \, ^\circ \text{C} / \text{mm} \). Therefore, the thermo-couple method has been applied, using the temperature/\( T_c \) vs. time relations for the carbide tool and the different workpiece materials. One is aware of the fact that the values measured in this way, represent values which are averaged over the contact area between tool and workpiece. Already during the start-up of the process about 90% of the maximum recorded temperature is reached. During the extrusion phase the contact temperature rises only slightly. When calibration starts, the temperature drops suddenly but quickly recovers while oscillating somewhat below the maximum level. Occasionally also the temperatures on the workpiece surface in the near vicinity of a growing bush have been measured. For this the thermo-couples were welded on the surface on concentric circles around the planned bush. Unfortunately the thermo-couples loosen at the moment the outer diameter of the bush reaches their position. So the measured max. values (see figure 6) can only be considered as the lower limits of the temperature in the extruding material.

### Load characteristics of the tool

Several factors are influencing the life time of the tool. Apart from the material properties of the tool, a table of influencing load factors is given below. Periodically changing thermal- and mechanical load components are causing both direct and indirect wear phenomena which are detrimental to tool life.

<table>
<thead>
<tr>
<th>Direct</th>
<th>Thermal-Load</th>
<th>Indirect</th>
<th>Mechanical-Load</th>
</tr>
</thead>
<tbody>
<tr>
<td>Thermal Stresses</td>
<td>DM</td>
<td>Corrosion, Diffusion</td>
<td>WM</td>
</tr>
<tr>
<td>Change of Material Properties</td>
<td>Abrasive Wear</td>
<td>Micro-cracks</td>
<td>Forming of Micro-cracks due to fatigue</td>
</tr>
</tbody>
</table>

**Notes:**
- DM: Non uniform and periodically changing temperatures are causing thermo-stress. It is experienced that with respect to tool life, thermo-stress is dominant in flow-drilling. Depending on the material properties, thermal-stresses can directly become fatal resulting in complete breakage of the carbide flow-drill. The resistance against thermo-stress of a material can be expressed by:
  - \( R_T = \text{Const.} \times \sigma_f \times \varepsilon_T \times \varepsilon_f \times k \)
  - where: \( \sigma_f \): fracture strength
  - \( \varepsilon_T \): fracture strain
  - \( k \): coefficient of heat transfer
- WM: The formula is used for choosing the right carbide grade. An analysis made of the thermal stresses showed the need for having a boring in the tool for diameters beyond 10-12 mm [1]. For diameters beyond 20 mm the size of the collar is gradually becoming the main limiting factor in tool life.

**IT:** Just like diffusion, corrosion of the tool material becomes an important problem in flow-drilling where temperatures close to the melting point of the workpiece material are readily possible. Experiments carried out with some K-10 grade on mild steel resulted in a quick deterioration of the surface of the tool by oxidation. This was followed by growing (micro-)cracks and these tools came to a total breakage within 80-150 bushes. The use of a TiC-TIN coating solved the oxidation problem but then a lack of hot-hardness caused plastic torsion of the cone and finally total breakage at nearly 1000 bushes (about 15% of normal tool life) [2].

**DM:** The mechanical load on the tool primarily consists of an axial force feed and a torsion moment. To give an idea of the order of magnitude: With a diameter of 12 mm and an axial force of 4 kN the normal stress on the facets of the tool is estimated to be 360 N/mm² while the corresponding tangential stress is 105 N/mm². (An estimate is made of the actual length of engagement of the facets). Reference made to the transfer rupture strength of about 2000 N/mm² yields that, on the basis of these values, fracture can hardly be expected. The tool-tip gradually becomes blunt by abrasive wear. Horn facets are not directly playing a significant part in tool life since total breakage occurs before the limiting tolerances of the diameter are exceeded. However, experiments have shown that the contact-temperature will rise about 100% by this. So tool life will be influenced.

**IT:** Flow-drilling in the case of a workpiece with a corroded surface proves to be very deleterious for the tool. It is believed that severe centration problems as a result of a delayed start-up are responsible for this. The quickly increasing feed force causes an axial force build-up which total breakage is to be expected (within a few bushes).

**DM:** Up till now it was not possible to indicate any significant influence.
EVALUATION OF EXPERIMENTAL RESULTS.

Temperatures
From the measured EXF-values it follows that the average contact-temperature $T_c$ is almost independent of the feed force $F_z$. The influence of the surface speed on $T_c$ is depicted in Fig. 7.

![Graph showing contact temperature $T_c$ vs. surface speed $V$](image)

Figure 7: Contact temperature $T_c$ vs. Surface Speed $V$.

The graph shows an asymptotic behaviour, the maximum of $T_c$ stabilising when approaching approximately $0.9 T_{mp}$ (melting point) the influence of the diameter of the tool (apart from the surface speed) and the material thickness can for the greater part be explained by a coherent increase in the active flow-drilling time (see also Fig. 10). It is quite possible that the measuring method in itself is also partly responsible for the observed influence of material thickness and tool diameter. The conclusion that for the usual applied surface speed of 1.5 m/s, the larger flow-drills are subjected to a significantly higher thermal load seems to be justified. This is confirmed by two facts:

1. Tool life decreases with the increasing diameter of the tool.
2. Observations show that the colour of a 16 mm tool may easily become bright-yellow while the smaller tools perform perceptibly cooler.

A remark should be made regarding the fact that in an automated environment the $T_c$ values of the smaller sized tools may shift somewhat towards higher numbers, this being the result of less cooling time.

For given process-conditions the temperature $T_c$ is dominated by the shear-stress/temperature relation belonging to the applied workplace material. When the surface speed is increased, the subsequent temperature rise will be limited. This happens as a result of the amount of energy which can be dissipated being limited by a drop in the shear-stress. The temperature will early stabilise at a point where both the supplied energy and the admissible energy are in equilibrium. This behaviour is indicated in Fig. 8 showing the curves representing the apparent coefficient of friction between tool and workplace as a function of $T_c$. This also explains why, within the feasible working range, the extrusion speed during bush formation is not significantly dependent on the feed force $F_z$.

Tool life
The number of bushes which can be made with one tool amounts from a few thousands for the larger sizes and for stainless steel to virtual infinity (for the smaller sizes and for copper). The main factors which are considered to determine tool life are:
- surface speed
- material properties of the tool
- tool size
- material properties of the workplace
- material thickness
- surface integrity of the workplace
- lubrication

Since tool-life tests are very time-consuming and extremely costly, no laboratory life-test have been carried out. The limited number of results presented in this section are calculated from data which are collected in industrial workshops. Their validity is limited in the sense that they are related to:
- an approximate surface speed of 1.5 m/s
- different non-specified values of the material thickness
- non-standardized lubrication conditions
- different non-specified low-carbon steels

The evaluation carried out with the aid of the Weibull Extreme Value Theory seems to be justified since the value of the calculated correlation factor in each case proves to be fair. The results presented below apply to a P25 carbide grade.

Experience gained over a long period of time shows that in the case of low-carbon steels and for diameters $> 10$ mm, tool life easily exceeds 20,000 bushes. In all cases, tool life is determined by total rupturing or total breakage. Cases in which a tool had to be changed because of intolerable wear on the calibration part, are not known.

The influence both of the material properties of the tool and of the surface integrity of the workplace on tool life has been discussed in the previous paragraph. The dominating influence of thermo-stress makes it possible to give a rough estimate of the influence of the workplace material on tool life: A low melting- point and a quickly dropping shear-stress/temperature curve will result in favourable machining characteristics and promote a long tool life.

![Table showing characteristic Weibull values](image)

<table>
<thead>
<tr>
<th>Diameter</th>
<th>12</th>
<th>13</th>
<th>19</th>
</tr>
</thead>
<tbody>
<tr>
<td>Number of specimens</td>
<td>23</td>
<td>6</td>
<td>10</td>
</tr>
<tr>
<td>Characteristic Weibull values</td>
<td>$T_{0,632}$</td>
<td>11.862</td>
<td>12.194</td>
</tr>
<tr>
<td>Correlation $r^2$</td>
<td>0.83</td>
<td>0.93</td>
<td>0.99</td>
</tr>
<tr>
<td>$T_{50%}$</td>
<td>11.700</td>
<td>11.388</td>
<td>9.437</td>
</tr>
<tr>
<td>$T_{90%}$</td>
<td>-</td>
<td>8.014</td>
<td>6.498</td>
</tr>
<tr>
<td>$T_{99%}$</td>
<td>7.000</td>
<td>7.007</td>
<td>5.635</td>
</tr>
</tbody>
</table>

$T_{99\%}$ - Tool life will be reached by probably 90% of the tool.

![Graph showing apparent coefficient of friction vs. contact temperature $T_c$](image)

Figure 8: Apparent Coefficient of Friction vs. Contact Temperature $T_c$.
The recorded flow-drilling times amount from a few to about 25 seconds. Fig. 9 shows the results as depicted in relation to the required specific power. (The washing-down phase is excluded.) The differentiation between the 16 mm tool and the others disappears when only the extension phase is taken into account (Fig. 10). The time which is needed to start up changes from about 1 second (9 mm) to about 10 seconds (16 mm). Fig. 10 shows that the numbers representing the extension time can be arranged to fit one single curve, regardless of the type of steel and service speed. It yields from Fig. 10 also that the required specific power decreases with increasing size of the tools. This behaviour complies with metal cutting where the specific energy decreases with increasing feed. Bauer and Kretschmer [7] reported 26 W/mm² for a 7 mm tool which is quite in agreement with the present findings.

REMARKS
- Attempts have been made to carry out a thorough dimensional analysis of the process but the results have been disappointing up till now.
- Both the present available results and the required data are urgently inviting continued research.
- Flow-drills are brought on the market by:
  - Flowdrill BV, Utrecht, Netherlands.
  - Drabus BV, Apeldoorn, Netherlands.

REFERENCES

LITERATURE